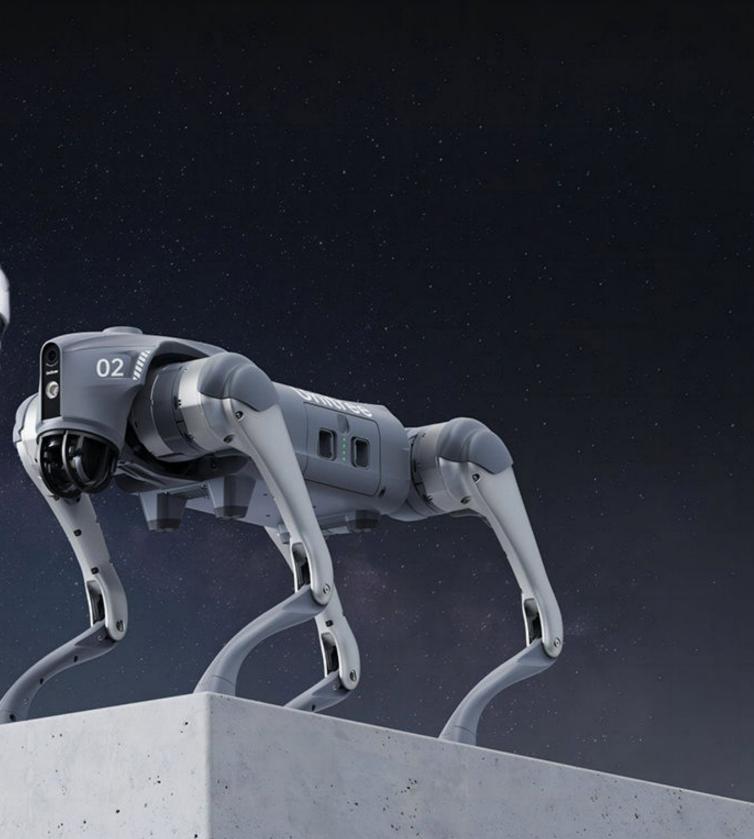
# ROBOTS

Al Robotic Companions Innovation in Motion





## **Unitree G1** Humanoid agent Al avatar

Introducing the Unitree G1, a revolutionary robotic platform that combines cutting-edge AI technology with exceptional mechanical engineering. Designed for flexibility, it features an impressive range of joint movement facilitated by 23 to 43 motors, allowing it to navigate complex environments effortlessly.

### Features

3D Lidar + Depth Camera

Moving Speed of 2m/s

Maximum Joint Torque 120 N.m

About 2 Hours Battery Life

Dex3-1 force Control Dexterous Hand

Weight About 35 kg

Height About 130 cm







### **Two Variant Available**

Model	G1
Height, Width and Thickness(Stand)	1320x450x200 mm
Height, Width and Thickness(Fold)	690x450x300mm
Weight (With Battery)	About 35kg
Total Degrees of Freedom(Joint Freedom)	23
Single Leg Degrees of Freedom	6
Waist Degrees of Freedom	1
Single Arm Degrees of Freedom	5
Single Hand Degrees of Freedom	
Joint output bearing	Industrial grade crossed roller bearings (high precision, high load capacity)
Joint motor	Low inertia high-speed internal rotor PMSM(permanent magnet synchronous motor,better response speed and heat dissipation)

#### G1 EDU

1320x450x200 mm

690x450x300mm

About 35kg+

23 - 43

6

1+(Optional 2 additional waist degrees of freedom)

5

7(Optional Force control of three-fingered hand)+2(Optional 2 additional wrist degrees of freedom)

\*Three-fingered dexterous hand Dex3-1 Parameter: The thumb has 3 active degrees of freedom; the index finger has 2 active degrees of freedom; the middle finger has 2 active degrees of freedom.

\*\*Dex3-1 can optionally be installed with tactile sensor arrays

Industrial grade crossed roller bearings (high precision, high load capacity)

Low inertia high-speed internal rotor PMSM(permanent magnet synchronous motor,better response speed and heat dissipation)

#### Model

Maximum Torque of Knee Joint(1)

Arm Maximum Load(2)

Calf + Thigh Length

Arm Span

Extra Large Joint Movement Space

90N.m

G1

About 2Kg

0.6M

About 0.45M

Waist joint: Z±155° Knee joint: 0~165° Hip joint: P±154°, R-30~+170°, Y±158°

Accessories

High Computing Power Module/Smart Battery (Quick Release)9000mAhCharger54V 5AManual ControllerYES

#### G1 EDU

120N.m

About 3Kg

0.6M

About 0.45M

Waist joint: Z±155°, X±45°, Y±30° Knee joint: 0~165° Hip joint: P±154°, R-30~+170°, Y±158° Wrist joint: P±92.5°, Y±92.5°

NVIDIA Jetson Orin

9000mAh

54V 5A

YES

#### Model G1 **Full Joint Hollow Electrical Routing** YES **Joint Encoder** Dual encoder Local air cooling **Cooling System** 13 string lithium battery **Power Supply Basic Computing Power** 8-core high-performance CPU Sensing Sensor Depth Camera+3D LiDAR 4 Microphone Array YES **5W Speaker** YES WiFi 6, Bluetooth 5.2 YES

Others

Battery Life	About 2h
Upgraded Intelligent OTA	YES
Secondary Development(3)	/

#### G1 EDU

#### YES

- Dual encoder
- Local air cooling
- 13 string lithium battery
- 8-core high-performance CPU
- Depth Camera+3D LiDAR
- YES
- YES
- YES
- About 2h
- YES
- YES

# **Unitree H1** Unitree's first universal humanoid robot

The Unitree H1 is an advanced humanoid robot designed to combine cutting-edge AI with practical capabilities. Equipped with dexterous manipulators, precise force control, and impressive movement range,

#### Features

3D Lidar + Depth Camera

Unitree M107 Joint Motor

Moving Speed of 3.3 m/s

Maximum Torque at Joints 360 N.m

Peak Torque Density 189N.m/Kg

Battery Capacity: 864Wh, Quickly Replaceable

Height About 180cm, Weight About 47kg



#### **Unitree H1 Parameter**

#### Model

**Key Dimensions** 

Thigh and Calf Length

Total Arm Length

DOF of Each Leg

**DOF of Each Arm** 

**Total Weight** 

Joint output bearing

**Core Joint motor** 

**Ultimate Torque of Joint Unit** 

Mobility

**Battery** 

**Control and Perception Computing Power** 

**Sensor Configuration** 

#### H1

(1520+285)mm × 570mm × 220mm

400mm × 2

338mm × 2

5(Hip×3 + Knee×1 + Ankle×1)

4(Expandable)

About 47kg

Industrial grade crossed roller bearings (high precision, high load capacity)

Low inertia high-speed internal rotor PMSM(permanent magnet synchronous motor,better response speed and heat dissipation)

Knee Torque About 360N.m, Hip Joint Torque About 220N.m, Ankle Torque About 59N.m, Arm Joint Torque About 75N.m

Moving speed of 3.3m/s(world record), Potential mobility > 5m/s

Battery capacity 15Ah(0.864KWh), Max Voltage 67.2V

Standard configuration: Intel Core i5(Platform Function) ,Intel Core i7(User Development) Optional Configuration: Intel Core i7 or Jetson Orin NX

3D LIDAR + Depth Camera

### **Unitree Go2** New Creature of Embodied AI

The Unitree Go2 is a next-generation quadruped robot designed for advanced mobility, adaptability, and AI-powered functionality. Equipped with Unitree's proprietary 4D LIDAR technology, it provides ultra-wide 360°x90° recognition, enabling precise navigation across various terrains with minimal blind spots.

### Features

3D LIDAR L1

ISS2.0 Intelligent Side-follow System

Maximum Running Speed 5m/s

Peak Joint Torque Approx. 45N.m

Wireless Module: Wi-Fi6/Bluetooth/4G

Ultra-long battery Endurance: Approx. 2h–4h





### **Three Variant Available**



Model	AIR	PRO
Dimension of standing	70x31x40cm	70x31x40cm
Dimension of crouching	76x31x20cm	76x31x20cm
Weight (With Battery)	About 15kg	About 15kg
Material	Aluminium alloy + High strength engineering plastic	Aluminium alloy + High strength engir
Voltage	28V~33.6V	28V~33.6V
Working maximum power	About 3000W	About 3000W
Payload	≈7kg MAX ~ 10kg	≈8kg MAX ~ 10kg
Speed	0 ~ 2.5m/s	0 ~ 3.5m/s
Max Climb Drop Height	About 15cm	About 16cm
Max Climb Angle	30°	40°
<b>Basic Computing Power</b>	/	8-core High-perforr

**Detailed Features** 



#### EDU

70x31x40cm

76x31x20cm

About 15kg

ineering plastic

Aluminium alloy + High strength engineering plastic

28V~33.6V

About 3000W

≈8kg MAX ~ 12kg 0 ~ 3.7m/s (MAX ~ 5m/s)

About 16cm

40°

rmance CPU 8-core High-performance CPU

Model	AIR	PRO
Max Joint Torque	/	About 45N.m
Aluminum knee joint motor	12 set	12 set
Range of Motion	body: -48~48° thigh: -200°~90° shank: -156°~-48°	body: -48~48° thigh: -200°~90° shank: -156°~-48°
Material	Aluminium alloy + High strength engineering plastic	Aluminium alloy + High strength engine
Intra-joint circuit (knee)	YES	YES
Joint Heat Pipe Cooler	YES	YES
Joint Heat Pipe Cooler	YES	YES
Wireless Vector Positioning Tracking Module	NO	YES
HD Wide-angle Camera	YES	YES
Foot-end force sensor	NO	NO
Basic Action	YES	YES
Auto-scaling strap	NO	YES
Upgraded Intelligent OTA	YES	YES
<b>RTT 2.0 Pictures Transaction</b>	YES	YES

**Detailed Features** 

	EDU
	About 45N.m
	12 set
	body: -48~48° thigh: -200°~90° shank: -156°~-48°
eering plastic	Aluminium alloy + High strength engineering plastic
	YES
	NO
	YES
	YES

Model	AIR	PRO
Graphical programme	YES	YES
Front lamp	YES	YES
WiFI6 with Dual-band	YES	YES
Bluetooth 5.2/4.2/2.1	YES	YES
4G module	NO	YES
Voice Function	NO	YES
ISS 2.0 Intelligent side-follow system	NO	YES
Wireless Vector Positioning Tracking Module	NO	YES
Intelligent detection and avoidance	YES	YES
Charging Pile Compatibility	NO	NO
Secondary development	NO	NO
High computing power module	NO	NO
Battery life	About 1-2h	About 1-2h
Smart battery	standard (8000mAh)	standard (8000r

**Detailed Features** 

# EDU YES YES YES YES YES YES YES YES YES

YES YES

NVIDIA Jetson Orin (optional) (40-100Topscomputing power)

About 2-4h

long endurance (15000mAh)

mAh)

### Unitree Go2 W Driving All Terrain

The Unitree Go2-W is an advanced quadruped robot designed for high agility, autonomy, and functionality. Tailored for industrial, educational, and research applications, it offers groundbreaking features such as real-time obstacle avoidance, versatile adaptability, and precision motion control.

### Features

Super-wide-angle 3D LIDAR

7 Inch Pneumatic Tire

Maximum Running Speed 2.5m/s

Peak Joint Torque Approx. 45N.m

Wireless Module: Wi-Fi6/Bluetooth/4G

Battery Endurance: Approx. 1.5h-3h

Weight About 18kg



#### **Parameter Details**

**Detailed Features** 

Dimension of standing	70cm x 43cm x 50cm	Manual controller	YES	
Weight (with battery)	About 18kg	Front Lighting Lamp	YES	
Voltage	33.6V	WIFI6&4G&Bluetooth	YES	
Payload	About 3kg	Voice Function	YES	
Speed	0~2.5m/s	Secondary development	YES	
Max Climb Drop Height	< 70cm	Expansion Module	Standard 100Tops arithmetic module (Orin NX)	
Max Climb Angle	35°	Battery Type	Long endurance(15000mAh)	
<b>Basic Computing Power</b>	8-core High-performance CPU	Endurance	1.5-3h	
Aluminum knee joint motor	16	Charger	Fast charge(33.6V 9A)	
Max Joint Torque	About 45N.m	<b>j</b>		
Tyres	7 Inch Pneumatic Tire			
Super-wide-angle 3D LIDAR	YES			
HD Wide-angle Camera	YES			
Basic Action	YES			
Upgraded Intelligent OTA	YES			
APP Support	YES			

# **Unitree B2** Go Beyond the Limits

The Unitree B2 is an advanced industrial-grade quadruped robot, redefining capabilities in robotic automation. Engineered to enhance performance in diverse industrial applications, it offers exceptional speed, agility, and endurance.

### Features

32 Wire Automotive-grade LiDAR

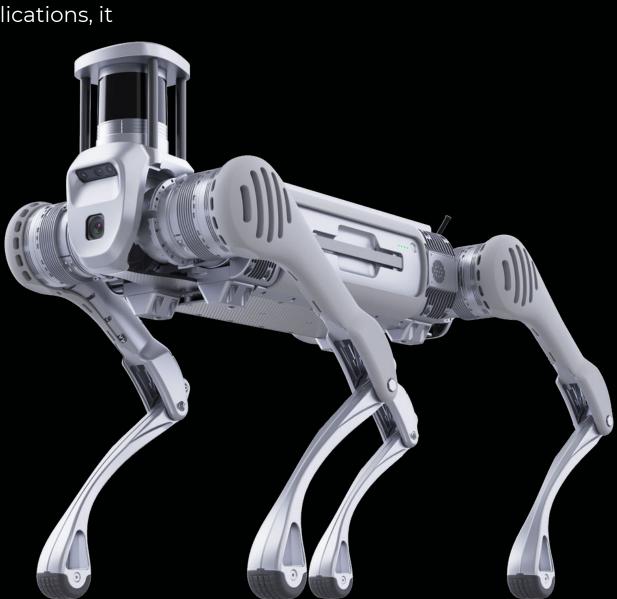
Max Running Speed 6m/s

Max Joint Torque About 360N.m

Longest Jump Distance 1.6m

Standing load: 120kg

Ultra Long Endurance 4-5 Hours





### **Unitree B2 Parameter**

Size(Standing)	≈ 1098mm×450mm×645mm	Ingress Protection	IP67
Size(Lying Prone)	≈ 880mm×460mm×330mm		Standard Configuration: Intel Core i5 (Platform Function), Intel Core i7 (User
Weight	≈ 60kg Total weight (battery included)	<b>Control and Perception</b>	Development) Optional Configuration: Intel Core i7 and Jetson Orin NX (Maximum up to 3 devices)
Battery Performance	Battery capacity 45Ah(2250Wh), voltage 58V		
	Battery life 4-6h	Ditch Jumping Width	0.5~1.2m
Endurance Ability	Walking without load > 5h, and the mileage > 20km	Max Jump Distance	> 1.6m
	Walking with 20kg load > 4h, and the mileage> 15km Sensing Sensor	3D LiDAR ×1 + Depth camera ×2 + Optical camera ×2 (Varies with different	
Wheeled Foot	Optional		configurations)
Load(Standing)	Max. 120kg	External Interface	1000M-Base-Ethernet×4 USB3.0×4 12V×4 5V×1 24V×4 BAT×1
Load(Walking)	> 40kg		
Continuous Stair Climbing	Stairs of 20~25cm		
Climbing Ability	Climb up and down stairs of 40cm in forward direction		
Operating Temperature	-20°c~ 55°c		
Climbing Angle	> 45°		
Running Speed	> 6m/s		

### Loona Meet Your Petbot

Loona is the ideal companion for families with kids, offering nonstop games, a lively personality, and smart AI interactions. Kids can ask questions, play, and even see their words come to life with AI-generated visuals, all controlled by simple voice commands for a fun and engaging experience.

#### Features

Facial Recognition

Intelligent Al

Leading Security

**Endless Games** 

Long Play

Amazing Sensors



# Add-ons Available



Loona charging dock

## **Eilik** Fun Unique Passionate

Meet Eilik, the desktop companion robot designed to bring a touch of emotional intelligence to your daily life. Created by Energize Lab, Eilik isn't just a gadget; it's a delightful interactive companion that brightens up your home or workspace.

#### Features

Dynamic Emotional States

Interactive Fun

Social Robot Play

Time Assistant & Playfellow

**Endless Potential** 

High-Quality Build







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